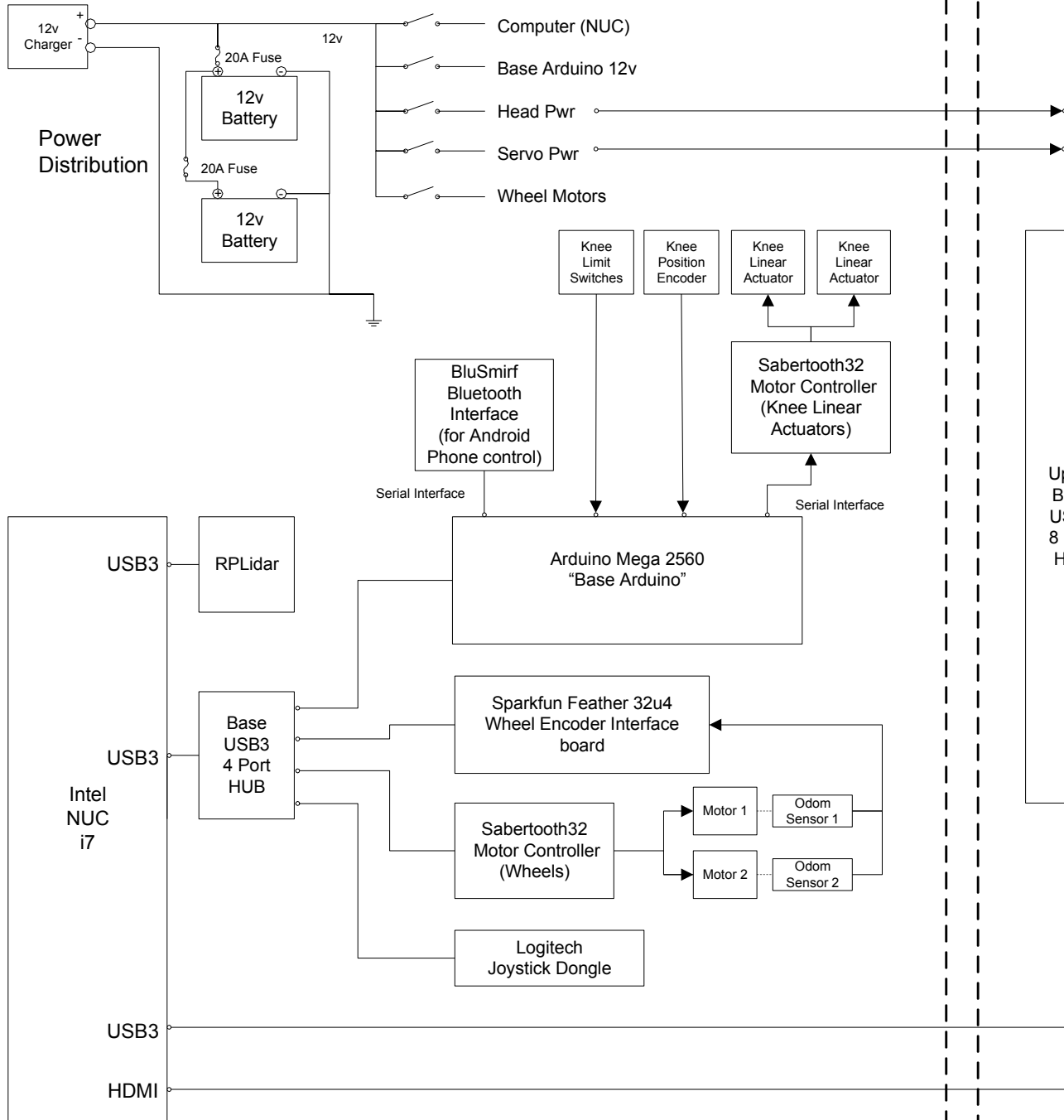
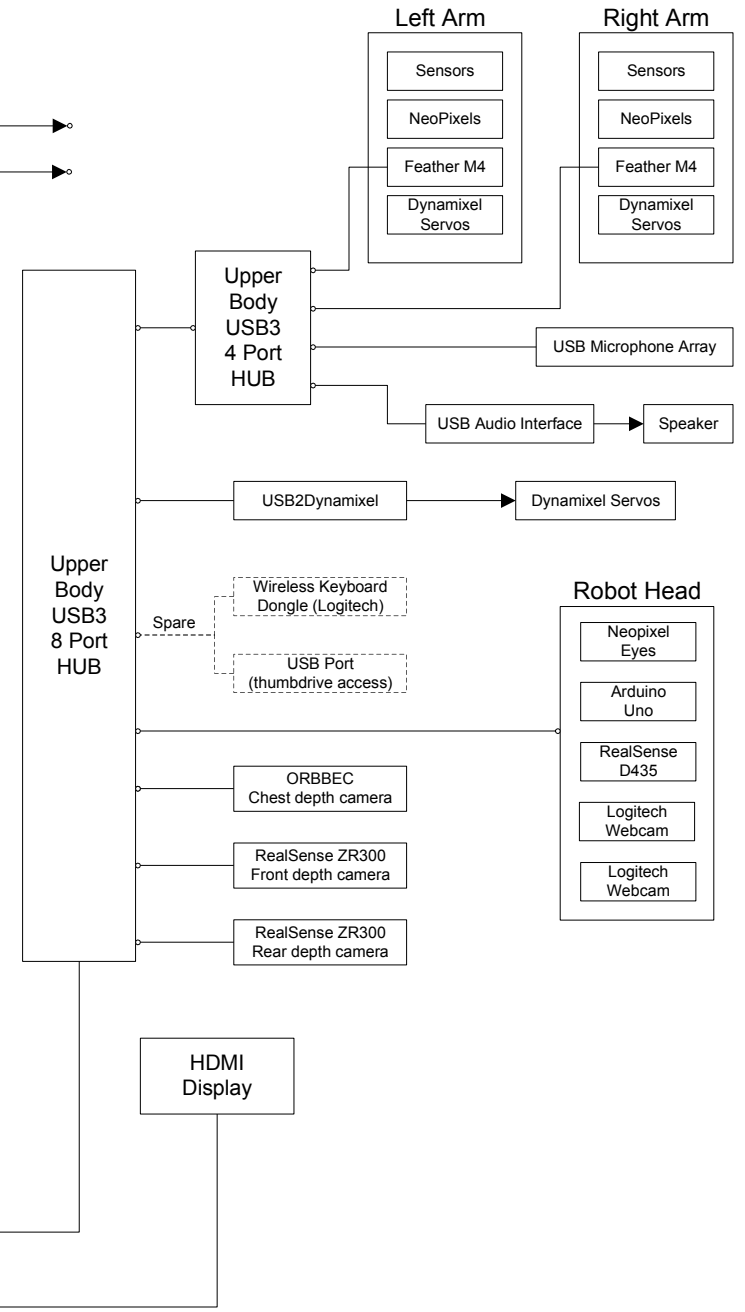
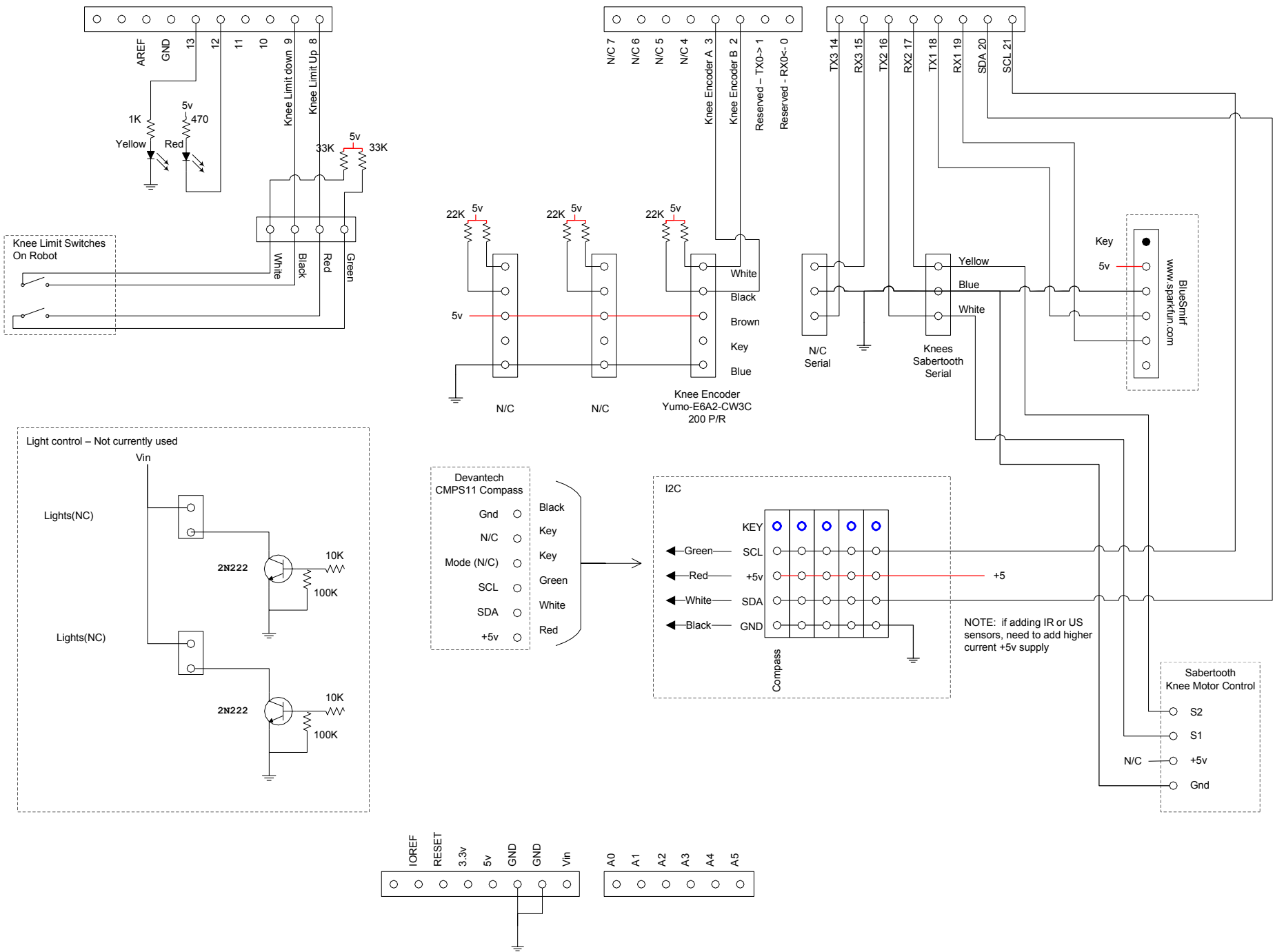


## Robot Base

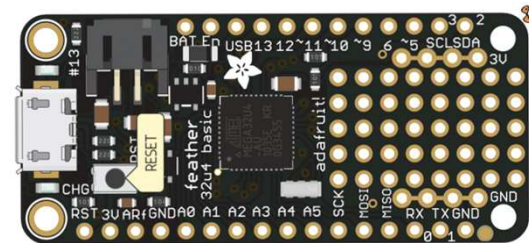
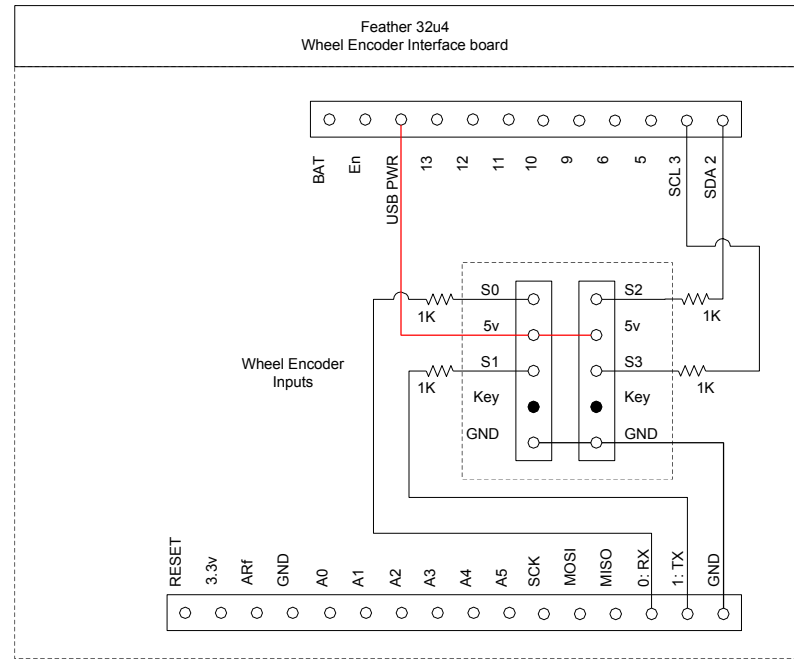
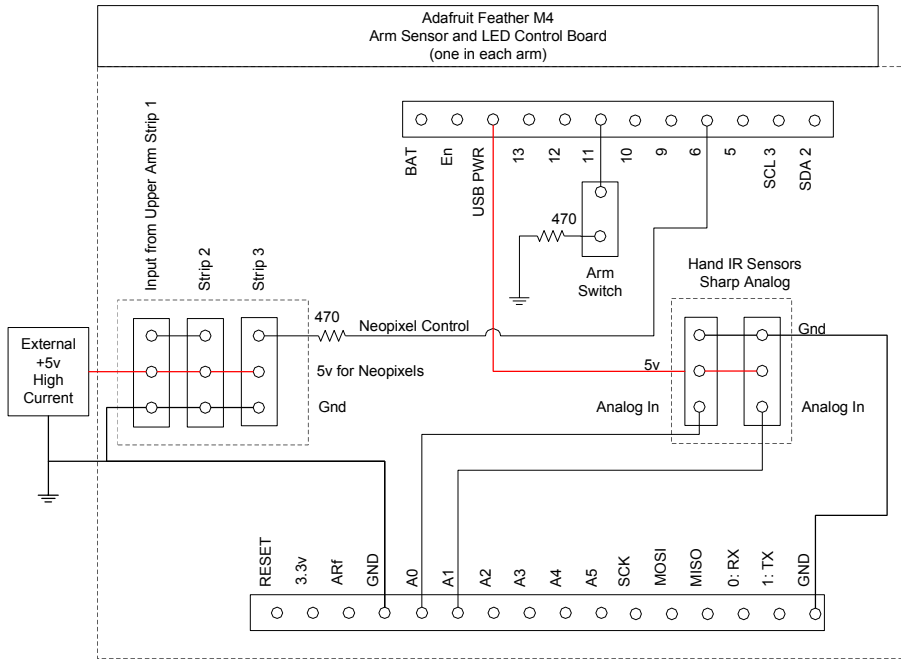


## Robot Body

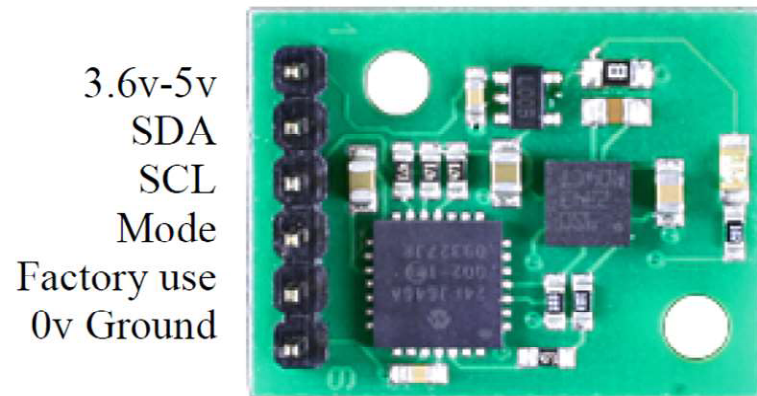
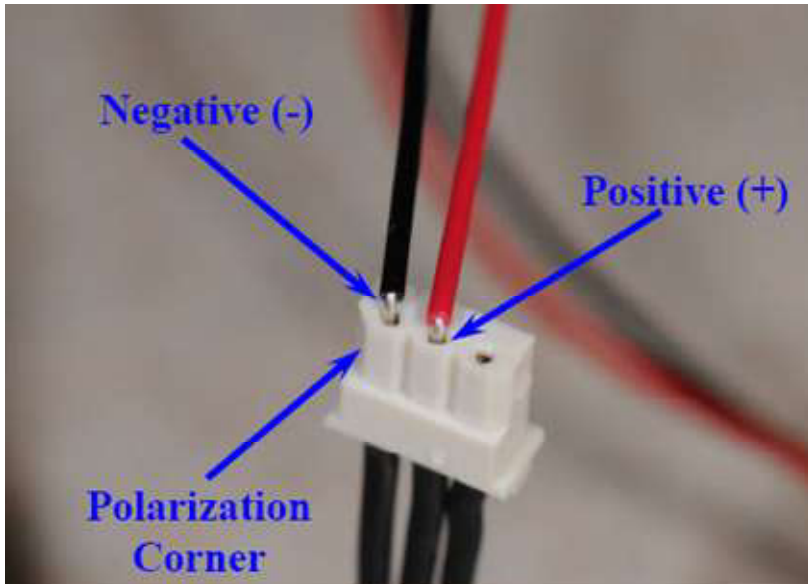




Sheldon Base Arduino Mega 2560 Interface Board



Dynamixel Servo Connection



To enter the I2C mode of operation leave the mode pin unconnected